Tutorial on Robust Auction Design Lecture 4

Instructors: Ben Brooks and Songzi Du

Slides @ https://benjaminbrooks.net/ https://econweb.ucsd.edu/~sodu/

EC 2021

The question

- You are a seller of a good
- You know the set of bidders
- You know the distribution of bidders values
- You are uncertain about the model of bidders' information
- You cannot (or won't) quantify this uncertainty in terms of a Bayesian prior
- What auction should you run?

An answer

In many cases, the auction you should run is proportional auction: A_i = ℝ₊ for each bidder *i*,

$$q_i^*(a) = rac{a_i}{\Sigma a} \cdot Q^*(\Sigma a), \qquad t_i^*(m) = rac{a_i}{\Sigma a} \cdot T^*(\Sigma a),$$

where $\Sigma a = \sum_{i=1}^{N} a_i$,

$$Q^*(\Sigma a) = egin{cases} \Sigma a / x & \Sigma a < x^*, \ 1 & \Sigma a \ge x^*. \end{cases}$$

Values

- A single unit for sale
- N bidders
- ▶ Value $v_i \in V_i \subset [0,\infty)$, $|V_i| < \infty$
- $\blacktriangleright v = (v_1, \ldots, v_N)$
- ▶ Prior $\mu \in \Delta(V)$

Mechanisms

A mechanism is a triple M = (A, q, t)
Finite actions A_i for i = 1,..., N
Action profiles A = A₁ × ··· × A_N
Allocations q : A → [0,1]^N, Σq(a) ≤ 1 (Σx = x₁ + ··· + x_N for x ∈ ℝ^N)
Transfers: t : A → ℝ^N

Mechanisms

A mechanism is a triple M = (A, q, t)
Finite actions A_i for i = 1,..., N
Action profiles A = A₁ × ··· × A_N
Allocations q : A → [0,1]^N, Σq(a) ≤ 1 (Σx = x₁ + ··· + x_N for x ∈ ℝ^N)
Transfers: t : A → ℝ^N

Participation security: For all *i*, there exists a action 0 ∈ A_i such that t_i(0, a_{-i}) = 0 ∀v_i, a_{-i}

Mechanisms

A mechanism is a triple M = (A, q, t)
Finite actions A_i for i = 1,..., N
Action profiles A = A₁ × ··· × A_N
Allocations q : A → [0,1]^N, Σq(a) ≤ 1 (Σx = x₁ + ··· + x_N for x ∈ ℝ^N)
Transfers: t : A → ℝ^N

- Participation security: For all i, there exists a action 0 ∈ A_i such that t_i(0, a_{-i}) = 0 ∀v_i, a_{-i}
- M set of participation-secure mechanisms

Information structures (aka type spaces)

• An information structure is a pair $\mathcal{I} = (S, \sigma)$

- Finite signals S_i
- Signal profiles $S = S_1 \times \cdots \times S_N$
- Joint distribution $\sigma \in \Delta(S \times V)$ where marginal on V is μ
- I is the set of information structures

Equilibrium

- Given $(\mathcal{M}, \mathcal{I})$, (behavioral) strategies $b_i : S_i \to \Delta(A_i)$
- $B(\mathcal{M},\mathcal{I})$ is the set of **Bayes Nash equilibria**
- Induced profit from b:

$$\Pi(\mathcal{M},\mathcal{I},b) = \sum_{v,s,a,i} t_i(a)b(a \mid s)\sigma(s,v)$$

A strong minimax theorem

```
Theorem Suppose \mu(v) > 0 for all v \in V. Then
```

$$\sup_{\mathcal{M}\in\boldsymbol{M}}\inf_{\mathcal{I}\in\boldsymbol{I}}\inf_{b\in\mathcal{B}(\mathcal{M},\mathcal{I})}\Pi(\mathcal{M},\mathcal{I},b)=\inf_{\mathcal{I}\in\boldsymbol{I}}\sup_{\mathcal{M}\in\boldsymbol{M}}\sup_{b\in\mathcal{B}(\mathcal{M},\mathcal{I})}\Pi(\mathcal{M},\mathcal{I},b).$$

- LHS is "MAX-2MIN", RHS is "MIN-2MAX"
- The value of these programs is Π*, the profit guarantee
- Equilibrium selection does not matter!

An even stronger theorem

We construct sequences of linear programs that, for a finite number of actions/signals, bound the MAX-2MIN and MIN-2MAX profits

For each $k \ge 1$ and *i*:

$$X_i(k) = \left\{0, \frac{1}{k}, \ldots, \frac{k^2 - 1}{k}, k\right\}$$

 $\blacktriangleright X(k) = \times_{i \in N} X_i(k)$

An even stronger theorem

We construct sequences of linear programs that, for a finite number of actions/signals, bound the MAX-2MIN and MIN-2MAX profits

For each $k \ge 1$ and *i*:

$$X_i(k) = \left\{0, \frac{1}{k}, \dots, \frac{k^2 - 1}{k}, k\right\}$$

X(k) = ×_{i∈N}X_i(k)
 M(k) are the participation-secure mechanisms with actions X(k)

$$\Pi^{\text{MAX}-2\text{MIN}}(k) = \sup_{\mathcal{M} \in \boldsymbol{M}(k)} \inf_{\mathcal{I} \in \boldsymbol{I}} \inf_{b \in B(\mathcal{M}, \mathcal{I})} \Pi(\mathcal{M}, \mathcal{I}, b)$$

An even stronger theorem

We construct sequences of linear programs that, for a finite number of actions/signals, bound the MAX-2MIN and MIN-2MAX profits

For each $k \ge 1$ and *i*:

$$X_i(k) = \left\{0, \frac{1}{k}, \dots, \frac{k^2 - 1}{k}, k\right\}$$

 $\blacktriangleright X(k) = \times_{i \in N} X_i(k)$

M(k) are the participation-secure mechanisms with actions X(k)

$$\Pi^{\text{MAX}-2\text{MIN}}(k) = \sup_{\mathcal{M} \in \boldsymbol{M}(k)} \inf_{\mathcal{I} \in \boldsymbol{I}} \inf_{b \in B(\mathcal{M}, \mathcal{I})} \Pi(\mathcal{M}, \mathcal{I}, b)$$

I(k) is the set of information structures with signal space
 X(k)

$$\Pi^{\mathrm{MIN-2MAX}}(k) = \inf_{\mathcal{I} \in I(k)} \sup_{\mathcal{M} \in \boldsymbol{M}} \sup_{b \in B(\mathcal{M}, \mathcal{I})} \Pi(\mathcal{M}, \mathcal{I}, b)$$

Discrete derivatives

Let f : X(k) → ℝ^N, and define the discrete upward partial derivative:

$$\nabla_{i}^{+} f(x) = \mathbb{I}_{x_{i} < k}(k-1)(f_{i}(x_{i}+1/k, x_{-i}) - f_{i}(x))$$

$$\nabla^{+} f(x) = (\nabla_{1}^{+} f(x), \dots, \nabla_{N}^{+} f(x))$$

$$\nabla^{+} \cdot f(x) = \sum_{i=1}^{N} \nabla_{i}^{+} f(x)$$

Linear relaxation for MAX-2MIN

$$\underline{\Pi}^{\text{MAX}-2\text{MIN}}(k) = \max_{\substack{q:X(k) \to \mathbb{R}^{N}, \ t:X(k) \to \mathbb{R}^{N}, \ \nu \in V}} \sum_{v \in V} \mu(v)\lambda(v) \\ \lambda: v \to \mathbb{R} \\ \text{s.t. } \Sigma q(x) \le 1 \ \forall x; \\ t_{i}(0, x_{-i}) = 0 \ \forall i, x_{-i}; \\ \lambda(v) \le \Sigma t(x) + v \cdot \nabla^{+}q(x) - \nabla^{+} \cdot t(x) \ \forall v, x$$
(1)

 Maximizing a lower bound on revenue across mechanisms, subject to local IC Linear relaxation for MAX-2MIN

min $\sigma > 0$ s.t. For a fixed mechanism, minimize the revenue across (local) Bayes correlated equilibria

$$(BCE) \qquad (D-BCE)$$

$$\underset{\sigma \ge 0}{\min} \sum_{x,v,i} t_i(x)\sigma(x,v) \qquad \qquad \underset{\alpha \ge 0,\lambda}{\max} \sum_{v} \mu(v)\lambda(v)$$
s.t.
$$\sum_{x} \sigma(x,v) = \mu(v) \ \forall v; \qquad \qquad \qquad \underset{\lambda(v) \le \Sigma t(x) \\ + \sum_{i,x_i} \alpha_i(x_i)(v_i \nabla_i^+ q(x) - \nabla_i^+ t(x)) \ \forall x,v \\ - \nabla_i^+ t(x_i, x_{-i})) \sigma(x_i, x_{-i}, v) \le 0 \ \forall i, x_i$$

Censored geometric distribution

Now define

$$\rho_i(x_i) = \left(1 - \frac{1}{k}\right)^{kx_i} \left(\frac{1}{k}\right)^{\mathbb{I}_{x_i < k}}$$

$$\rho(\mathbf{x}) = \prod_{i=1}^{N} \rho_i(\mathbf{x}_i)$$

• (PMF of the censored geometric with arrival rate 1/k)

Linear relaxation for MIN-2MAX

$$\overline{\Pi}^{\text{MIN-2MAX}}(k) = \min_{\substack{\sigma:X(k) \times V \to \mathbb{R}_+, \ w:X(k) \to \mathbb{R}^n, \\ \gamma:X(k) \to \mathbb{R}_+}} \sum_{x \in X(k)} \gamma(x)$$
s.t.
$$\sum_{x \in X(k)} \sigma(x, v) = \mu(v) \ \forall v;$$

$$\sum_{x \in V} \sigma(x, v) = \rho(x) \ \forall x;$$

$$w(x) = \frac{1}{\rho(x)} \sum_{v \in V} v \sigma(x, v) \ \forall x$$

$$\gamma(x) \ge \rho(x) \left[w_i(x) - \nabla_i^+ w(x) \right] \ \forall x;$$
(2)

Minimizing the highest virtual value across information structures where the signal distribution is ρ Linear relaxations converge as $k \to \infty$

Theorem For all k > 0, $\overline{\Pi}^{\text{MIN}-2\text{MAX}}(k) \ge \Pi^{\text{MIN}-2\text{MAX}}(k) \ge \Pi^{\text{MAX}-2\text{MIN}}(k) \ge \underline{\Pi}^{\text{MAX}-2\text{MIN}}(k)$. If $\mu(v) > 0$ for all $v \in V$, then $\lim_{k \to \infty} \overline{\Pi}^{\text{MIN}-2\text{MAX}}(k) = \lim_{k \to \infty} \Pi^{\text{MAX}-2\text{MIN}}(k) = \Pi^*$

$$\lim_{k \to \infty} \prod^{\text{MAX}-2\text{MIN}}(k) = \lim_{k \to \infty} \underline{\prod}^{\text{MAX}-2\text{MIN}}(k) = \Pi^*$$

Linear relaxations converge as $k \to \infty$

Theorem For all k > 0, $\overline{\Pi}^{\text{MIN}-2\text{MAX}}(k) \ge \Pi^{\text{MIN}-2\text{MAX}}(k) \ge \Pi^{\text{MAX}-2\text{MIN}}(k) \ge \underline{\Pi}^{\text{MAX}-2\text{MIN}}(k).$ If $\mu(v) > 0$ for all $v \in V$, then

$$\lim_{k\to\infty}\overline{\Pi}^{\mathrm{MIN-2MAX}}(k) = \lim_{k\to\infty}\underline{\Pi}^{\mathrm{MAX-2MIN}}(k) = \Pi^*.$$

Moreover,

- If (q, t) solves (1), then profit in (X(k), q, t) is at least <u>Π</u>^{MAX−2MIN}(k) for any information structure and equilibrium.
- If σ solves (2), then profit in (X(k), σ) is at most Π^{MIN-2MAX}(k) in any mechanism and equilibrium.

Two programs

(1)

$$\begin{split} \max_{q \geq 0, t, \lambda} & \sum_{v} \mu(v) \lambda(v) \\ \text{s.t. } & \Sigma q(x) \leq 1 \ \forall x \\ & t_i(0, x_{-i}) = 0 \ \forall i, x_{-i}; \\ & \lambda(v) \leq \Sigma t(x) \\ & + v \cdot \nabla^+ q(x) - \nabla^+ \cdot t(x) \ \forall x, v \end{split}$$

(2)

$$\begin{split} \min_{\sigma \ge 0, \gamma \ge 0, w} & \sum_{x} \gamma(x) \\ \text{s.t.} & \sum_{x} \sigma(x, v) = \mu(v) \ \forall v; \\ & \sum_{v} \sigma(x, v) = \rho(x) \ \forall x; \\ & w_i(x) = \frac{1}{\rho(x)} \sum_{v} v_i \sigma(x, v) \ \forall i, x; \\ & \gamma(x) \ge \rho(x) [w_i(x) - \nabla_i^+ w_i(x)] \ \forall i, x \end{split}$$

Solving out transfers from (1)

- In program (2), we "solved out" the transfers
- Can do the same thing in (1):
 - Let Ξ(x) = ∇⁺ · t(x) − Σt(x) denote the aggregate excess growth
 - For fixed Ξ, there exists a t that satisfies this equation iff ∑_x ρ(x)Ξ(x) = 0 (implied by, e.g., Farkas' lemma)
- So, in program (1), we can substitute in Ξ for t and add the expectation of Ξ to the objective:

Two programs

$$(1')$$

$$\max_{\lambda,q\geq 0,t} \sum_{v} \mu(v)\lambda(v) + \sum_{x} \rho(x)\Xi(x)$$
s.t. $\Sigma q(x) \leq 1 \ \forall x;$

$$\lambda(v) + \Xi(x) \leq v \cdot \nabla^{+}q(x) \ \forall x, v.$$
s.t.

$$\begin{split} \min_{\sigma \ge 0, \gamma \ge 0, w} & \sum_{x} \gamma(x) \\ \text{s.t.} & \sum_{x} \sigma(x, v) = \mu(v) \; \forall v; \\ & \sum_{v} \sigma(x, v) = \rho(x) \; \forall x; \\ & w_i(x) = \frac{1}{\rho(x)} \sum_{v} v_i \sigma(x, v) \; \forall i, x; \\ & \gamma(x) \ge \rho(x) [w_i(x) - \nabla_i^+ w_i(x)] \; \forall i, x \end{split}$$

(2)

(1') and dual of (2)

$$(1') \tag{D-2}$$

$$\max_{\lambda, \Xi, q \ge 0} \sum_{v} \mu(v)\lambda(v) + \sum_{x} \rho(x)\Xi(x) \qquad \max_{\Xi, \lambda, q \ge 0} \sum_{v} \mu(v)\lambda(v) + \sum_{x} \rho(x)\Xi(x)$$
s.t. $\Sigma q(x) \le 1 \ \forall x;$
 $\lambda(v) + \Xi(x) \le v \cdot \nabla^{+}q(x) \ \forall x, v \qquad \lambda(v) + \Xi(x) \le v \cdot \nabla^{-}q(x) \ \forall x, v$

Shifting

- We complete the proof of the theorem by showing that (1') and (2) have almost the same value when k is large
- They are "almost" a dual pair, except for the direction of local IC

Shifting

- We complete the proof of the theorem by showing that (1') and (2) have almost the same value when k is large
- They are "almost" a dual pair, except for the direction of local IC
- Given a feasible q for (D-2), we construct a feasible q' for (1'), so that (1') and (2) have almost the same value
- ▶ If q' is non-decreasing, can use:

$$q'_i(x) = \begin{cases} q_i(x_i - 1/k, x_{-i}) & \text{if } x_i > 0; \\ 0 & \text{if } x_i = 0 \end{cases}$$

Shifting

- We complete the proof of the theorem by showing that (1') and (2) have almost the same value when k is large
- They are "almost" a dual pair, except for the direction of local IC
- Given a feasible q for (D-2), we construct a feasible q' for (1'), so that (1') and (2) have almost the same value
- If q' is non-decreasing, can use:

$$q'_i(x) = \begin{cases} q_i(x_i - 1/k, x_{-i}) & \text{if } x_i > 0; \\ 0 & \text{if } x_i = 0 \end{cases}$$

- Complication: If q decreases, could have $\Sigma q'(x) > 1$
- ► Last step: decrease in q is bounded below, and the bound goes to zero faster than 1/k ⇒ we can "rescale" q' to make it feasible without significantly changing the objective

As $k \to \infty$

$\Pi^{\rm MAX-2MIN}$

$$\max_{\lambda,q\geq 0,t} \sum_{v} \mu(v)\lambda(v) + \sum_{x} \rho(x)\Xi(x)$$

s.t. $\Sigma q(x) \leq 1 \ \forall x; [\gamma(x)]$ $\lambda(\mathbf{v}) + \Xi(\mathbf{x}) \leq \mathbf{v} \cdot \nabla q(\mathbf{x}) \; \forall \mathbf{x}, \mathbf{v}; [\sigma(\mathbf{x}, \mathbf{v})]$

$$\overline{\Pi}^{\rm MIN-2MAX}$$

$$\min_{\substack{\sigma \ge 0, \gamma \ge 0, w}} \sum_{x} \gamma(x)$$

s.t.
$$\sum_{x} \sigma(x, v) = \mu(v) \ \forall v; [\Xi(x)]$$
$$\sum_{v} \sigma(x, v) = \rho(x) \ \forall x; [\lambda(v)]$$
$$w_i(x) = \frac{1}{\rho(x)} \sum_{v} v_i \sigma(x, v) \ \forall i, x;$$
$$\gamma(x) \ge \rho(x) [w_i(x) - \nabla_i w_i(x)] \ \forall i, x; [q_i(x)]$$

Suppose the two programs are an exact dual pair as $k \to \infty$

~

Then at the optimal, complementary-slackness conditions should hold

Binary common values

- Suppose $v_i \in \{0, 1\}$, and $\mu(\{v_1 = v_2 = \cdots = v_N\}) = 1$.
- ▶ That is, the seller only knows the expected common value.

Binary common values

- Suppose $v_i \in \{0,1\}$, and $\mu(\{v_1 = v_2 = \cdots = v_N\}) = 1$.
- That is, the seller only knows the expected common value.

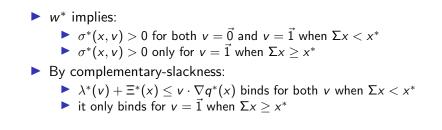
• As
$$k \to \infty$$
, $\rho_i(x_i) = \exp(-x_i)$.

Value function:

$$w_i^*(x) = egin{cases} C \exp(\Sigma x) & \Sigma x < x^* \ 1 & \Sigma x \ge x^* \end{cases}$$

- All bidders have the same virtual value, which is 0 if Σx < x* and is 1 otherwise
- ► The last constraint in <u>Π</u>^{MAX-2MIN} is always binding, so q^{*}_i(x) is free to be interior

MAX-2MIN mechanisms



MAX-2MIN mechanisms

w* implies:
σ*(x, v) > 0 for both v = 0 and v = 1 when Σx < x*
σ*(x, v) > 0 only for v = 1 when Σx ≥ x*
By complementary-slackness:
λ*(v) + Ξ*(x) ≤ v · ∇q*(x) binds for both v when Σx < x*
it only binds for v = 1 when Σx ≥ x*
With some additional regularity and boundary conditions, an allocation q is MAX-2MIN optimal as long as ∇_iq(x) = 1/x* (< 1/x*) if Σx < x* (≥ x*)

For example, these conditions are satisfied by the proportional allocation:

$$q_i^*(x) = \frac{x_i}{\max\{x^*, \Sigma x\}}$$

Transfers

▶ We show that for any such allocation,

$$\Xi^*(x) = \nabla \cdot q^*(x) - \lambda^*(\vec{1})$$

satisfies $\int_{\mathbb{R}^N_+} \Xi^*(x) \rho(dx) = 0$

> As a result, there always exists a transfer rules that solves

$$\Xi^*(x) = \nabla \cdot t(x) - \Sigma t(x)$$

Transfers

We show that for any such allocation,

$$\Xi^*(x) = \nabla \cdot q^*(x) - \lambda^*(\vec{1})$$

satisfies $\int_{\mathbb{R}^N_+} \Xi^*(x) \rho(dx) = 0$

As a result, there always exists a transfer rules that solves

$$\Xi^*(x) = \nabla \cdot t(x) - \Sigma t(x)$$

For the proportional allocation q*, there is a transfer that solves this equation and has the proportional form:

$$t_i^*(x) = q_i^*(x) T^*(\Sigma x),$$

where T^* solves an ODE

We call this MAX-2MIN mechanism proportional auction.

Truthful equilibrium

- In the finite bounding programs, we use a revelation principle, so the strategies are truthful/obedient
- Another heuristic for the continuum limit is that truthtelling/obedience should be locally optimal at the saddle point
- In fact, we show directly that the truthful/obedient strategies are an equilibrium for the saddle point we construct

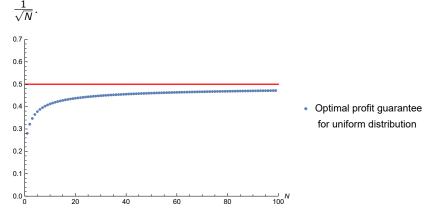
Robustness of proportional auction

- If the value is common but not binary, proportional auction remains MAX-2MIN optimal.
- If each bidder's expected value is known and the same, but the correlation and information structure are unknown, proportional auction remains MAX-2MIN optimal.
 - Common value is the worst-case (MIN-2MAX) information structure.

Common value full surplus extraction

Proposition

The profit guarantee of the proportional auction converges to the full surplus (expected common value) as $N \to \infty$ at the rate of



Literature

- Bergemann, Brooks and Morris (2017), Brooks and Du (2021a,b,c)
- Robustness to correlation under private value: He and Li (2020), Zhang (2021)
- Distributional robustness under private value: Che (2020)
- Robustness to strategic uncertainty: Yamashita (2015)
- Robustness to resale opportunity: Carroll and Segal (2018)

Conclusion

- Linear programs that compute the optimal profit guarantee over all information structures and equilibria
- In many cases, the optimal (MAX-2MIN) mechanism is the proportional auction
- Guarantees full surplus extraction in common value setting with large markets
- Open questions:
 - Lower bounds on information? Private values?
 - Simple mechanisms that guarantee a good approximation of the full surplus?
 - Other welfare criteria? (Minmax regret for social surplus?)
 - Relax equilibrium assumption? (Rationalizability? Adaptive agents?)